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Mapping near-inertial variability in the SE Bay of Biscay from HF radar data and two offshore moored buoys

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Introduction





Introduction: the HF radar system main characteristics

Matxitxako Antenna (transmitter and receiver) and electronics. Two radial site stations: HIger (Donostia) and Matxitxako Central combine site in Vitoria

> WORKING SINCE 2009

MAIN CARACTERISTICS of the BASQUE SYSTEM

F	Radar	Radar	Ocean	Depth of	Typical	Typical	Typical	Upper H _{1/3}
	Frequency	Wavelengtł	Wavelength	Current ¹	Range²	Resolution ⁻	Bandwidth	Limit ⁴
	(MHz)	(m)	(m)	(m)	(km)	(km)	(kHz)	(m)
	4.86	60	30	2-3	~150	~ 5	30	25



Introduction: the HF radar system main characteristics

FROM CROSS SPECTRA TO RADIAL VELOCITIES

MUSIC (MUItiple SIgnal Classification) Algorithm

[Schmidt, R.O., (1986), IEEE Trans. Antennas Propagat., vol. AP-34, pp. 276-280]

•Linear solutions based on eigen-analysis of averaged spectral covariances

•Capable of more than two solutions with little added numerical burden

•Chooses the number of bearings based on both eigenvalue & amplitude ratios

•Capable of incorporating measured, distorted antenna patterns

OUTPUT: Vectors in polar coordinate system centered at receiving antenna:

 1 radial map per averaged cross spectra file
 Typically, seven radial maps "merged" into one hourly map (3-hours running average)
 Angular resolution is 5°



Introduction: the HF radar system main characteristics

FROM RADIAL TO TOTAL VELOCITIES

Several radials from each site contribute to each total vector, being resolved into orthogonal components (U, V)

Linear least squares performed on U, V components separately

From radials with:

 An angle of incidence greater than α α min = 30°
 And total velocities < 120 cm/s

Defining a
•GRID SPACING: 5km
•AVERAGING RADIUS: of 20 KM



HF radar vs. In-situ data

HF RADAR (4.5 MHz) integrates currents vertically within the first 2-3 m of the water column. Radial resolution= 5km; angular reolution 5°; 3h running window hourly data.





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HF radar vs. In-situ data

Radar





ADC 1,5 m



HF radar vs. In-situ data

- Dispersion model applied to radar data to reproduce the observed trajectory
- Radar-derived trajectory: smaller amplitude (? Smoothing of data) and mean drift direction rotated to the W (? Ekman)





Distribution of near-inertial KE

- 10th order digital Butterworth band pass filter [Emery and Thomson, 2001] applied to each velocity component
 - near-inertial: pass band 14 h <T<20 h
 - sub-inertial : low pass T>30

Example for the nearinertial pass band

Distribution of near-inertial KE (cm²/s²)

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Isobaths: 200, 1000 and 2000 m.

Distribution of near-inertial KE (cm²/s²)-Connection with background field?

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???

SUMMER

- Weaker and more variable winds, predominantly from the NW
- anticlyclonic pattern with negative vorticity offshore of 200 bathy
- Stratification, thermocline at 50 m
- The surface near-inertial KE values are much more intense and centred in the middle of the Landes plateau.
- Surface intensification of the near-inertial oscillations due to stratification.
- Weak negative RV background field which would favour the oscillations (but it is too weak to explain the observed distribution).

WINTER

- Intense winds (mainly SW)
- Well-defined cyclonic pattern, positive vorticity over the slope
- Well-mixed water column
- Less intense near-inertial KE, confined in the NW of the domain, over the deeper part of the slope
- Much weaker near-inertial oscillations at surface levels. Deeper mixed layer, and thus less amplitude generation
- Winter background cyclonic circulation much more intense. The near-inertial oscillations decrease in areas where the mean flow is intense and present strong RV positive values (upper slope).

No clear impact of background field (at least in summer when it is weak)
 Impact of the seasonal differences in atmospheric/buoyancy forcings
 The summer-winter difference might be also due to wave propagation characteristics (Cg) and interaction with coast and bathymetry.

Merci!

